

NAG Fortran Library Routine Document

F08KGF (SORMBR/DORMBR)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

F08KGF (SORMBR/DORMBR) multiplies an arbitrary real matrix C by one of the real orthogonal matrices Q or P which were determined by F08KEF (SGBRD/DGBRD) when reducing a real matrix to bidiagonal form.

2 Specification

```

SUBROUTINE F08KGF(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
1              LWORK, INFO)
ENTRY          sormbr (VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
1              LWORK, INFO)
INTEGER       M, N, K, LDA, LDC, LWORK, INFO
real        A(LDA,*), TAU(*), C(LDC,*), WORK(*)
CHARACTER*1   VECT, SIDE, TRANS

```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine is intended to be used after a call to F08KEF (SGBRD/DGBRD), which reduces a real rectangular matrix A to bidiagonal form B by an orthogonal transformation: $A = QBP^T$. F08KEF represents the matrices Q and P^T as products of elementary reflectors.

This routine may be used to form one of the matrix products

$$QC, Q^T C, CQ, CQ^T, PC, P^T C, CP \text{ or } CP^T,$$

overwriting the result on C (which may be any real rectangular matrix).

4 References

Golub G H and van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

Note: in the description below, r denotes the order of Q or P^T : $r = M$ if SIDE = 'L' and $r = N$ if SIDE = 'R'.

1: VECT – CHARACTER*1 *Input*

On entry: indicates whether Q or Q^T or P or P^T is to be applied to C as follows:

if VECT = 'Q', Q or Q^T is applied to C ;

if VECT = 'P', P or P^T is applied to C .

Constraint: VECT = 'Q' or 'P'.

2: SIDE – CHARACTER*1 *Input*

On entry: indicates how Q or Q^T or P or P^T is to be applied to C as follows:

if SIDE = 'L', Q or Q^T or P or P^T is applied to C from the left;

if SIDE = 'R', Q or Q^T or P or P^T is applied to C from the right.

Constraint: SIDE = 'L' or 'R'.

3: TRANS – CHARACTER*1 *Input*

On entry: indicates whether Q or P or Q^T or P^T is to be applied to C as follows:

if TRANS = 'N', Q or P is applied to C ;

if TRANS = 'T', Q^T or P^T is applied to C .

Constraint: TRANS = 'N' or 'T'.

4: M – INTEGER *Input*

On entry: m_C , the number of rows of the matrix C .

Constraint: $M \geq 0$.

5: N – INTEGER *Input*

On entry: n_C , the number of columns of the matrix C .

Constraint: $N \geq 0$.

6: K – INTEGER *Input*

On entry: if VECT = 'Q', the number of columns in the original matrix A ; if VECT = 'P', the number of rows in the original matrix A .

Constraint: $K \geq 0$.

7: A(LDA,*) – *real* array *Input/Output*

Note: the second dimension of the array A must be at least $\max(1, \min(r, K))$ if VECT = 'Q' and at least $\max(1, r)$ if VECT = 'P'.

On entry: details of the vectors which define the elementary reflectors, as returned by F08KEF (SGBERD/DGBERD).

On exit: used as internal workspace prior to being restored and hence is unchanged.

8: LDA – INTEGER *Input*

On entry: the first dimension of the array A as declared in the (sub)program from which F08KGF (SORMBR/DORMBR) is called.

Constraints:

$LDA \geq \max(1, r)$ if VECT = 'Q',

$LDA \geq \max(1, \min(r, K))$ if VECT = 'P'.

9: TAU(*) – *real* array *Input*

Note: the dimension of the array TAU must be at least $\max(1, \min(r, K))$.

On entry: further details of the elementary reflectors, as returned by F08KEF (SGBERD/DGBERD) in its parameter TAUQ if VECT = 'Q', or in its parameter TAUP if VECT = 'P'.

10: C(LDC,*) – *real* array *Input/Output*

Note: the second dimension of the array C must be at least $\max(1, N)$.

On entry: the matrix C .

On exit: C is overwritten by QC or $Q^T C$ or CQ or CQ^T or PC or $P^T C$ or CP or CP^T as specified by VECT, SIDE and TRANS.

11: LDC – INTEGER *Input*

On entry: the first dimension of the array C as declared in the (sub)program from which F08KGF (SORMBR/DORMBR) is called.

Constraint: $LDC \geq \max(1, M)$.

12: WORK(*) – *real* array *Workspace*

Note: the dimension of the array WORK must be at least $\max(1, LWORK)$.

On exit: if INFO = 0, WORK(1) contains the minimum value of LWORK required for optimum performance.

13: LWORK – INTEGER *Input*

On entry: the dimension of the array WORK as declared in the (sub)program from which F08KGF (SORMBR/DORMBR) is called, unless LWORK = -1, in which case a workspace query is assumed and the routine only calculates the optimal dimension of WORK (using the formula given below).

Suggested value: for optimum performance LWORK should be at least $N \times nb$ if SIDE = 'L' and at least $M \times nb$ if SIDE = 'R', where *nb* is the **blocksize**.

Constraints:

$$\begin{aligned} LWORK &\geq \max(1, N) \text{ or } LWORK = -1 \text{ if SIDE} = \text{'L'}, \\ LWORK &\geq \max(1, M) \text{ or } LWORK = -1 \text{ if SIDE} = \text{'R'}. \end{aligned}$$

14: INFO – INTEGER *Output*

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -*i*, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed result differs from the exact result by a matrix *E* such that

$$\|E\|_2 = O(\epsilon)\|C\|_2,$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of floating-point operations is approximately

$$2n_C k(2m_C - k) \text{ if SIDE} = \text{'L'} \text{ and } m_C \geq k;$$

$$2m_C k(2n_C - k) \text{ if SIDE} = \text{'R'} \text{ and } n_C \geq k;$$

$$2m_C^2 n_C \text{ if SIDE} = \text{'L'} \text{ and } m_C < k;$$

$$2m_C n_C^2 \text{ if SIDE} = \text{'R'} \text{ and } n_C < k;$$

where *k* is the value of the parameter K.

The complex analogue of this routine is F08KUF (CUNMBR/ZUNMBR).

9 Example

For this routine two examples are presented. Both illustrate how the reduction to bidiagonal form of a matrix A may be preceded by a QR or LQ factorization of A .

In the first example, $m > n$, and

$$A = \begin{pmatrix} -0.57 & -1.28 & -0.39 & 0.25 \\ -1.93 & 1.08 & -0.31 & -2.14 \\ 2.30 & 0.24 & 0.40 & -0.35 \\ -1.93 & 0.64 & -0.66 & 0.08 \\ 0.15 & 0.30 & 0.15 & -2.13 \\ -0.02 & 1.03 & -1.43 & 0.50 \end{pmatrix}.$$

The routine first performs a QR factorization of A as $A = Q_a R$ and then reduces the factor R to bidiagonal form B : $R = Q_b B P^T$. Finally it forms Q_a and calls F08KGF (SORMBR/DORMBR) to form $Q = Q_a Q_b$.

In the second example, $m < n$, and

$$A = \begin{pmatrix} -5.42 & 3.28 & -3.68 & 0.27 & 2.06 & 0.46 \\ -1.65 & -3.40 & -3.20 & -1.03 & -4.06 & -0.01 \\ -0.37 & 2.35 & 1.90 & 4.31 & -1.76 & 1.13 \\ -3.15 & -0.11 & 1.99 & -2.70 & 0.26 & 4.50 \end{pmatrix}.$$

The routine first performs an LQ factorization of A as $A = L P_a^T$ and then reduces the factor L to bidiagonal form B : $L = Q B P_b^T$. Finally it forms P_b^T and calls F08KGF (SORMBR/DORMBR) to form $P^T = P_b^T P_a^T$.

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
*      F08KGF Example Program Text
*      Mark 16 Release. NAG Copyright 1992.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
      INTEGER          MMAX, NMAX, LDA, LDPT, LDU, LWORK
      PARAMETER        (MMAX=8,NMAX=8,LDA=MMAX,LDPT=NMAX,LDU=MMAX,
+
      real           ZERO
      PARAMETER        (ZERO=0.0e0)
*      .. Local Scalars ..
      INTEGER          I, IC, IFAIL, INFO, J, M, N
*      .. Local Arrays ..
      real           A(LDA,NMAX), D(NMAX), E(NMAX-1), PT(LDPT,NMAX),
+
      TAU(NMAX), TAUP(NMAX), TAUQ(NMAX), U(LDU,NMAX),
+
      WORK(LWORK)
*      .. External Subroutines ..
      EXTERNAL        sgebrd, sgelqf, sgqrqf, sorglq, sorgqr, sormbr,
+
      F06QFF, F06QHF, X04CAF
*      .. Executable Statements ..
      WRITE (NOUT,*) 'F08KGF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
      DO 20 IC = 1, 2
         READ (NIN,*) M, N
         IF (M.LE.MMAX .AND. N.LE.NMAX) THEN
*
*           Read A from data file
*

```

```

      READ (NIN,*) ((A(I,J),J=1,N),I=1,M)
*
      IF (M.GE.N) THEN
*
*       Compute the QR factorization of A
*
      CALL sgeqrf(M,N,A,LDA,TAU,WORK,LWORK,INFO)
*
      Copy A to U
*
      CALL F06QFF('Lower',M,N,A,LDA,U,LDU)
*
      Form Q explicitly, storing the result in U
*
      CALL sorgqr(M,M,N,U,LDU,TAU,WORK,LWORK,INFO)
*
      Copy R to PT (used as workspace)
*
      CALL F06QFF('Upper',N,N,A,LDA,PT,LDPT)
*
      Set the strictly lower triangular part of R to zero
*
      CALL F06QHF('Lower',N-1,N-1,ZERO,ZERO,PT(2,1),LDPT)
*
      Bidiagonalize R
*
      CALL sgebrd(N,N,PT,LDPT,D,E,TAUQ,TAUP,WORK,LWORK,INFO)
*
      Update Q, storing the result in U
*
      CALL sormbr('Q','Right','No transpose',M,N,N,PT,LDPT,
+           TAUQ,U,LDU,WORK,LWORK,INFO)
*
      Print bidiagonal form and matrix Q
*
      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Example 1: bidiagonal matrix B'
      WRITE (NOUT,*) 'Diagonal'
      WRITE (NOUT,99999) (D(I),I=1,N)
      WRITE (NOUT,*) 'Super-diagonal'
      WRITE (NOUT,99999) (E(I),I=1,N-1)
      WRITE (NOUT,*)
      IFAIL = 0
*
      CALL X04CAF('General',' ',M,N,U,LDU,
+           'Example 1: matrix Q',IFAIL)
*
      ELSE
*
*       Compute the LQ factorization of A
*
      CALL sgelqf(M,N,A,LDA,TAU,WORK,LWORK,INFO)
*
      Copy A to PT
*
      CALL F06QFF('Upper',M,N,A,LDA,PT,LDPT)
*
      Form Q explicitly, storing the result in PT
*
      CALL sorglq(N,N,M,PT,LDPT,TAU,WORK,LWORK,INFO)
*
      Copy L to U (used as workspace)
*
      CALL F06QFF('Lower',M,M,A,LDA,U,LDU)
*
      Set the strictly upper triangular part of L to zero
*
      CALL F06QHF('Upper',M-1,M-1,ZERO,ZERO,U(1,2),LDU)
*
      Bidiagonalize L
*

```

```

      CALL sgebrd(M,M,U,LDU,D,E,TAUQ,TAUP,WORK,LWORK,INFO)
*
*      Update P**T, storing the result in PT
*
      CALL sormbr('P','Left','Transpose',M,N,M,U,LDU,TAUP,PT,
+          LDPT,WORK,LWORK,INFO)
*
*      Print bidiagonal form and matrix P**T
*
      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Example 2: bidiagonal matrix B'
      WRITE (NOUT,*) 'Diagonal'
      WRITE (NOUT,99999) (D(I),I=1,M)
      WRITE (NOUT,*) 'Super-diagonal'
      WRITE (NOUT,99999) (E(I),I=1,M-1)
      WRITE (NOUT,*)
      IFAIL = 0
*
      CALL X04CAF('General',' ',M,N,PT,LDPT,
+          'Example 2: matrix P**T',IFAIL)
*
      END IF
      END IF
20 CONTINUE
      STOP
*
99999 FORMAT (3X,(8F8.4))
      END

```

9.2 Program Data

F08KGF Example Program Data

6	4						:Values of M and N, Example 1
-0.57	-1.28	-0.39	0.25				
-1.93	1.08	-0.31	-2.14				
2.30	0.24	0.40	-0.35				
-1.93	0.64	-0.66	0.08				
0.15	0.30	0.15	-2.13				
-0.02	1.03	-1.43	0.50				:End of matrix A
4	6						:Values of M and N, Example 2
-5.42	3.28	-3.68	0.27	2.06	0.46		
-1.65	-3.40	-3.20	-1.03	-4.06	-0.01		
-0.37	2.35	1.90	4.31	-1.76	1.13		
-3.15	-0.11	1.99	-2.70	0.26	4.50		:End of matrix A

9.3 Program Results

F08KGF Example Program Results

Example 1: bidiagonal matrix B

Diagonal

3.6177 -2.4161 1.9213 -1.4265

Super-diagonal

1.2587 -1.5262 1.1895

Example 1: matrix Q

	1	2	3	4
1	-0.1576	-0.2690	0.2612	0.8513
2	-0.5335	0.5311	-0.2922	0.0184
3	0.6358	0.3495	-0.0250	-0.0210
4	-0.5335	0.0035	0.1537	-0.2592
5	0.0415	0.5572	-0.2917	0.4523
6	-0.0055	0.4614	0.8585	-0.0532

Example 2: bidiagonal matrix B

Diagonal

-7.7724 6.1573 -6.0576 5.7933

Super-diagonal

1.1926 0.5734 -1.9143

Example 2: matrix P**T

	1	2	3	4	5	6
1	-0.7104	0.4299	-0.4824	0.0354	0.2700	0.0603
2	0.3583	0.1382	-0.4110	0.4044	0.0951	-0.7148
3	-0.0507	0.4244	0.3795	0.7402	-0.2773	0.2203
4	0.2442	0.4016	0.4158	-0.1354	0.7666	-0.0137
